



Interactive Walkthroughs using Multiple GPUs

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SIGGRAPH COURSE #11, 2003

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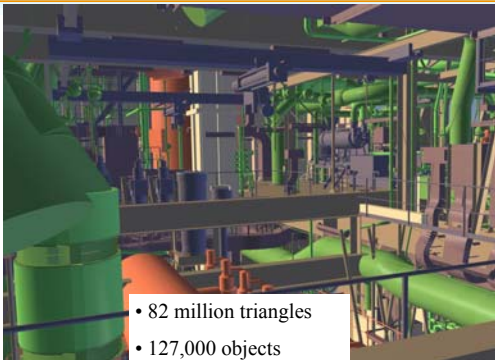
Goal

- Interactive Walkthrough of *complex 3D* environments at *high fidelity*
 - ◆ Models from CAD, VR
 - ◆ High primitive count
 - ◆ Heterogeneous geometry
 - ◆ Irregular distribution

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DoubleEagle Tanker Model



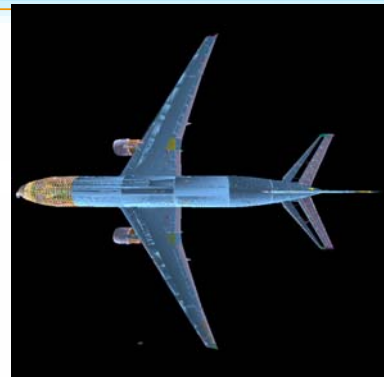
- 82 million triangles
- 127,000 objects

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Boeing 777

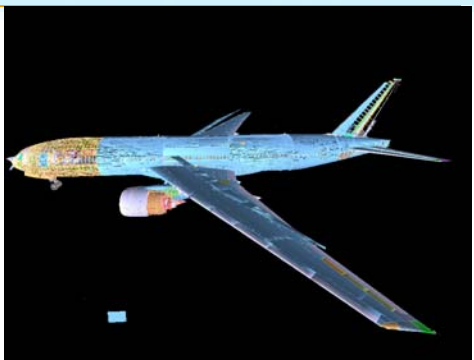
470 million triangles




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 **Boeing 777**

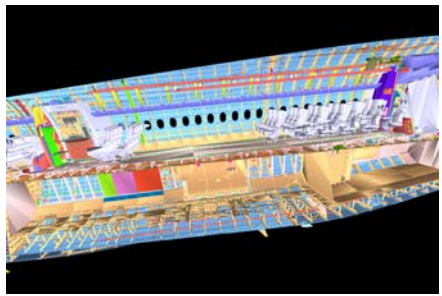
470 million triangles




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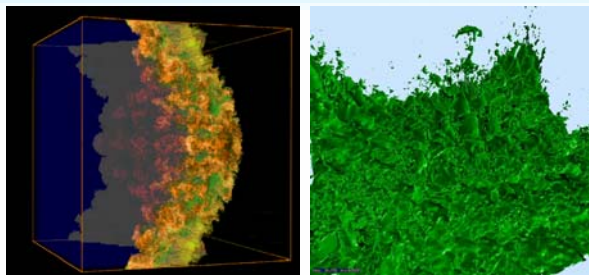
 **Boeing 777**

470 million triangles:
Zoomed in View



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 **Simulation of Richtmyer-Meshkov instability**



2048 * 2048 * 1920 grid and 27,000 time steps
(5832 processors, IBM SST System):
Over 3 TB of multivariate data generated.
Each time step, ~500 Million triangles for each iso-surface

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 **Simulation of Richtmyer-Meshkov instability**



Close view of a small detail
Data: Lawrence Livermore Labs

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Commodity Hardware Performance

- Current GPUs have capabilities to render millions of polygons per second
- Require vertex arrays, triangle stripping to achieve these rates
- **Issues**
 - ◆ Large polygon count
 - ◆ Memory limitations

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Commodity Hardware Performance

- Current GPUs have capabilities to render millions of polygons per second
- Require vertex arrays, triangle stripping to achieve these rates
- **Issues**
 - ◆ Large polygon count
 - ◆ Memory limitations
- **Solution** – Reduce polygon count

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Acceleration Techniques

- Geometric simplification
- Occlusion culling
- Hybrid approaches

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Geometric Simplification

- Static [Clark 1976; Hoppe 96; Erikson et al. 01; Garland et al. 97]
- View-Dependent [Hoppe 97; Luebke et al. 97]
- Surveyed in LOD book [Luebke et al. 02]



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Occlusion Culling

- Cells and portals [Airey et al. 90; Teller 92; Luebke et al. 95]
- Urban datasets composed of large occluders [Coorg et al. 97; Hudson et al. 97; Schaufler et al. 00; Wonka et al. 01]
- Recent survey in [Cohen-Or et al. 02]
- Further classified as
 - ◆ Conservative [Greene et al. 93, Zhang et al. 97]
 - ◆ Approximate [Bartz et al. 99; Klosowski and Silva 00]

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Hybrid Approaches

- Combine LOD and Occlusion Culling techniques
 - ◆ UC Berkeley Walkthrough [Funkhouser et al. 96]
 - ◆ Synthetic convex occluders [Andujar et al. 00]
 - ◆ Approximate visibility using prioritized layer projections with view dependent rendering [EISana et al. 01]
 - ◆ UNC MMR system [Aliaga et al. 99]
 - ◆ GigaWalk [Baxter et al. 02]

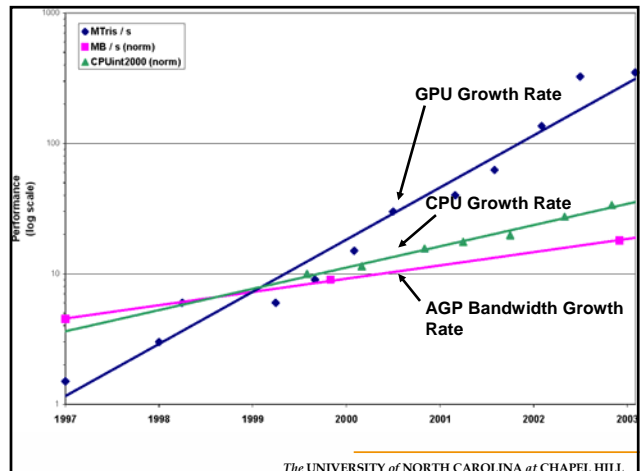
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Motivation

- An algorithm that works on generic models
- Image-based culling algorithms
- Current approaches involve frame buffer readbacks [Greene et al. 93, Zhang et al. 97, Baxter et al. 02]

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Frame Buffer Readbacks

- GPU growth rate is higher than Moore's law
- Bandwidth growth rate lower than Moore's law
 - ◆ Result – Frame buffer readbacks are expensive
 - ◆ Also readbacks result in graphics pipeline stalls
- Require a solution that
 - ◆ Leverages high GPU power
 - ◆ Avoids frame buffer readbacks

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Outline

- Parallel algorithm using multiple GPUs
- Interactive walkthroughs
- Interactive shadow generation

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- **Parallel algorithm using multiple GPUs**
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Occlusion-Switch

- Occlusion-switch has 2 GPUs
 - ◆ It takes a camera as input
 - ◆ The output is PVS and a camera

PVS: Potentially visible set

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Occlusion-Switch

- Parallel image-based culling algorithm
- A novel switching mechanism to eliminate frame-buffer readbacks
- Exploits temporal coherence
 - ◆ Occluder selection
 - ◆ Lower bandwidth requirements
- Integrates with hierarchical LODs

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Occlusion Switch : Parallel Algorithm and Architecture

- **Three processes in parallel**
 1. **Occlusion Representation (OR)**
 2. **Hardware Culling (HC)**
 3. **Render Visible Geometry (RVG)**

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Timing/Data Flow

HC
GPU₁ Hardware Cull
for Frame *i*

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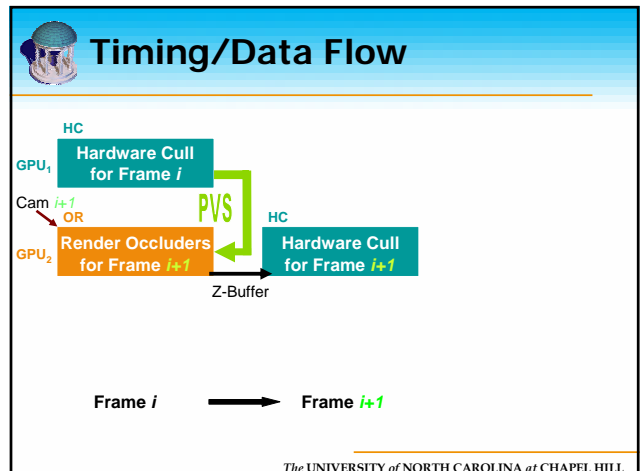
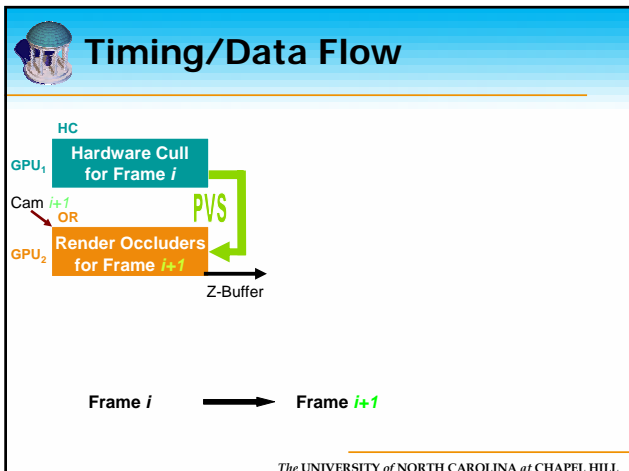
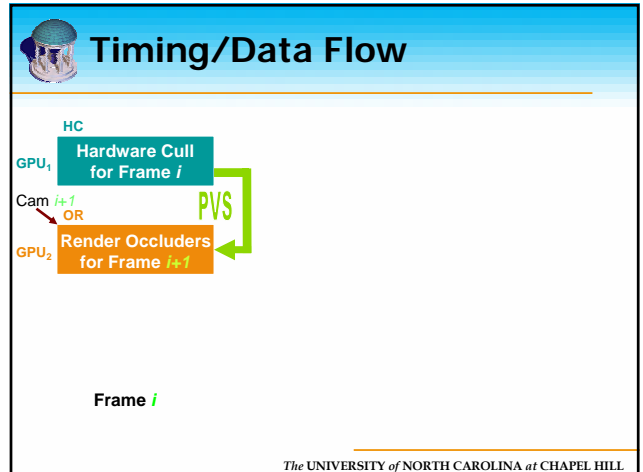
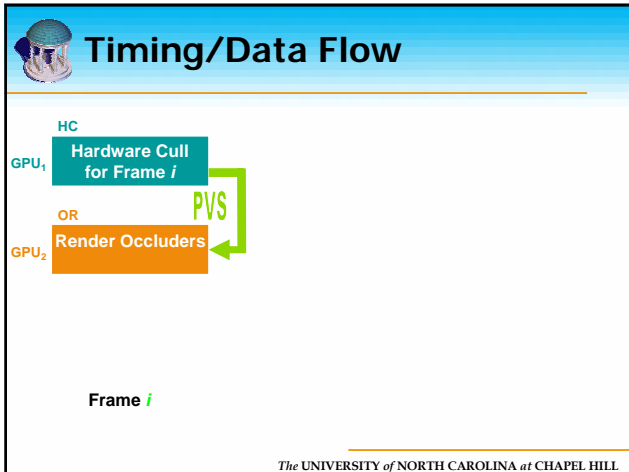


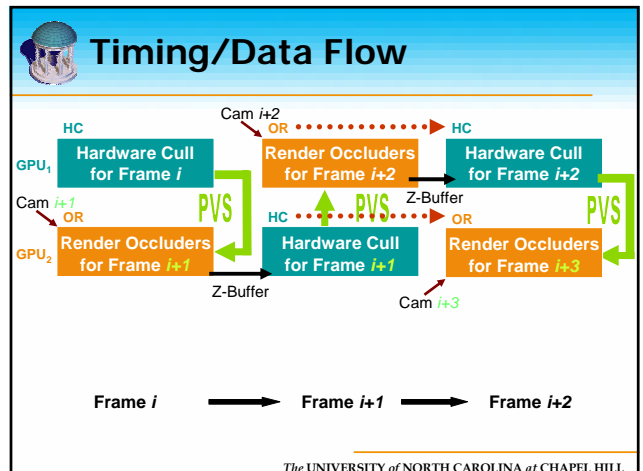
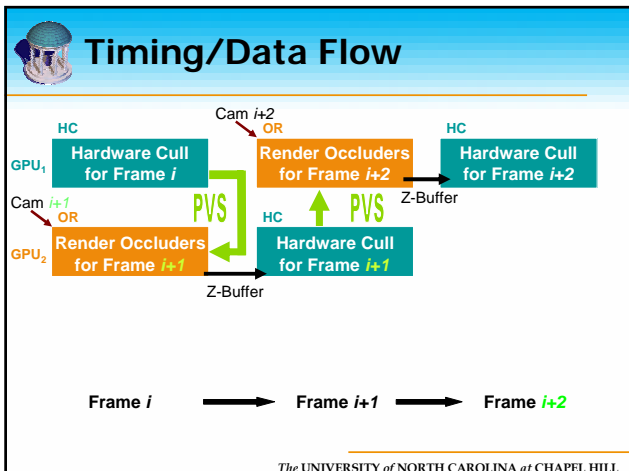
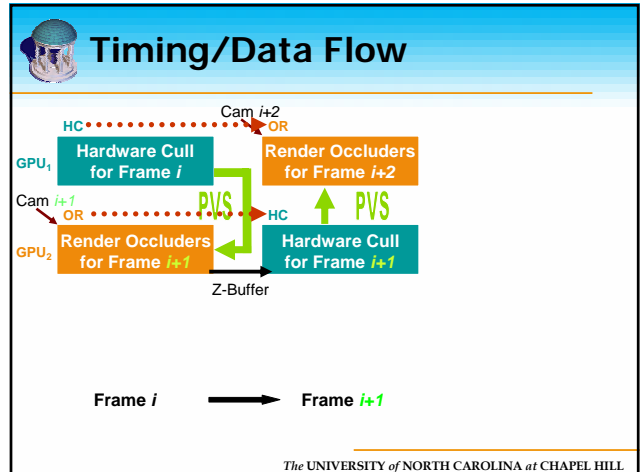
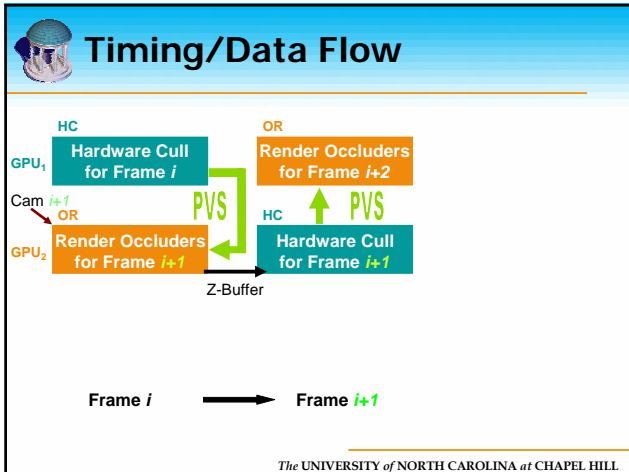
Timing/Data Flow

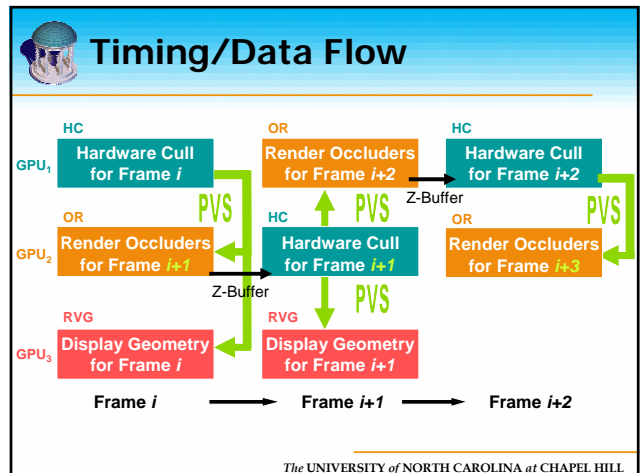
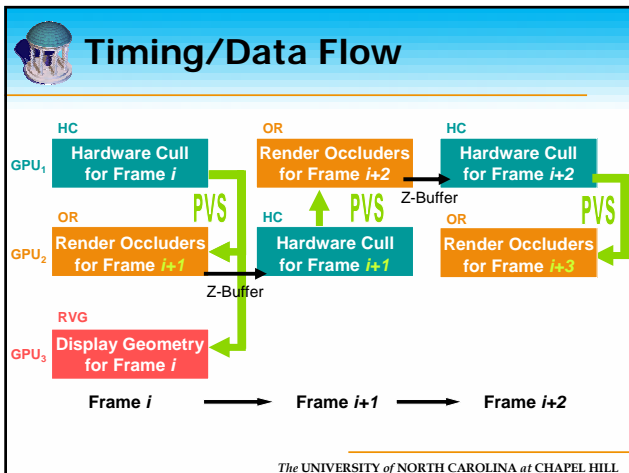
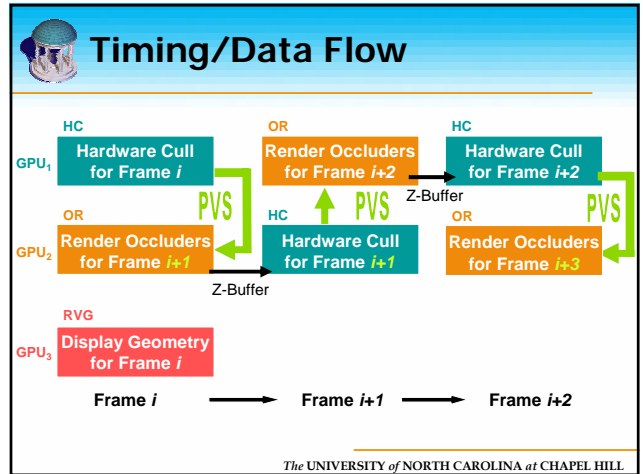
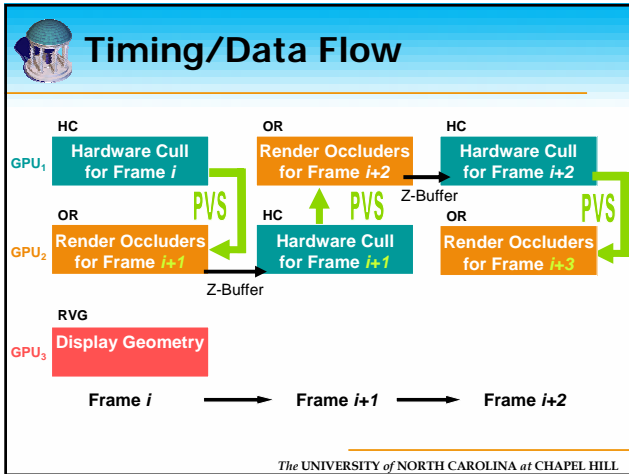
HC
GPU₁ Hardware Cull
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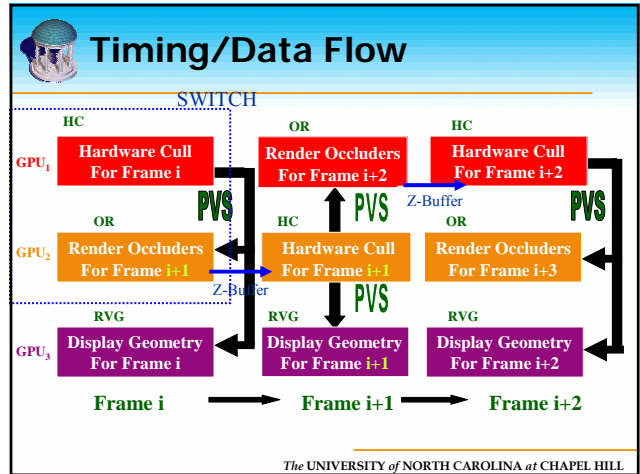
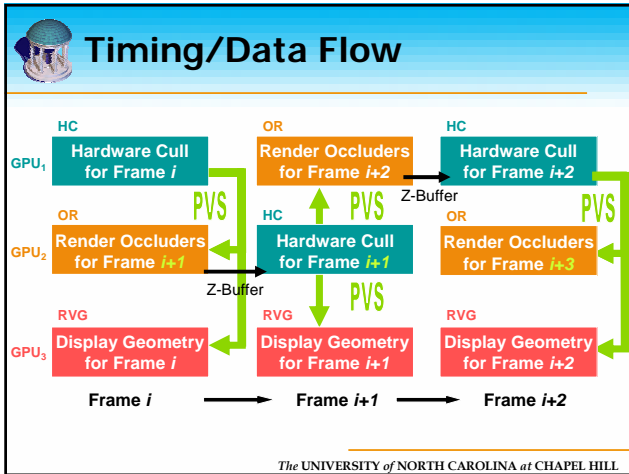
OR
GPU₂ Render Occluders

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Bandwidth Requirements

- Potential Visible Set (PVS) and camera parameters are transmitted over the network.
- Temporal coherence to minimize bandwidth requirements
 - ◆ Each GPU maintains current frame geometry
 - ◆ Transmit the differences in visible geometry across successive frames

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Static LOD Selection: Error Metric

- Pixel Error Metric: Max normal deviation of silhouette in image
- Traverse down scene graph till error satisfied
- Upper Bound: Highly conservative

DE Engine Room 1K x 1K, 20 PE

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Hardware Culling

- Use NV_OCCLUSION_QUERY to determine visible pixels
- Traverse scene hierarchy rendering bounding boxes of nodes

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Hardware Culling Optimizations

- **Multiple Occlusion Tests**
 - ◆ Occlusion Query 'counter' for each node
 - ◆ Traverse scene graph breadth first
 - ◆ Bunch queries for all nodes at a level
 - ◆ 40% faster than testing one node with HP_OCCLUSION_TEST

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LOD Selection: Visibility Metric

- **Visibility for LOD selection**
 - ◆ Visible pixels of bounding box > visible pixels of geometry
 - ◆ No. of visible pixels less than error metric provides an early termination condition
 - ◆ Provides looser bounds – reduces polygon count

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Conservative Occlusion Culling

- Underlying algorithm used for occlusion culling is conservative to image precision
- Exactly same set of LODs is used for both OR and HC stages

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Outline

- Parallel algorithm using multiple GPUs
- **Interactive walkthroughs**
- Interactive shadow generation

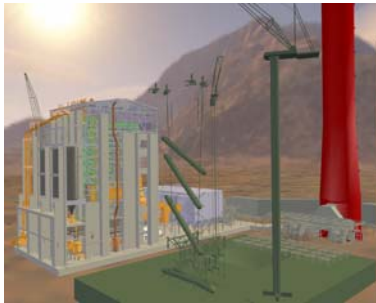
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Interactive Walkthroughs

- 3 Dell Precision Workstations with dual 2 GHz Pentium IV CPUs, GeForce 4 GPU, and 2 GB main memory: **Immediate mode rendering**

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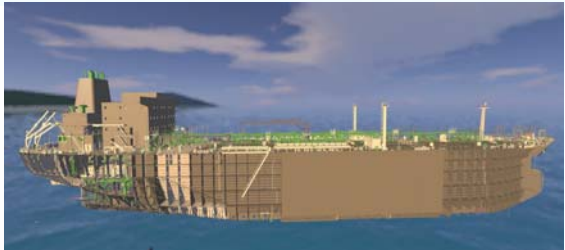
Test Model: Powerplant



- Original**
 - 0.5 Gigabyte dataset
 - 13 Million Polygons
 - 1200 objects
- Preprocessing**
 - 7 hours
 - 1.2 Gigabytes
 - 13 Million Polygons
 - 38,000 objects

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Test Model: DoubleEagle Tanker



- Original**
 - 4 Gigabyte dataset
 - 82 Million polygons
 - 127,000 objects
- Preprocessing**
 - 34 hours
 - 8 Gigabytes
 - 82 Million polygons
 - 61,000 objects

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Interactive Walkthrough: Powerplant



13M triangles: 3 Dell PCs with
NVIDIA GeForce 4 cards (2002)

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Interactive Walkthrough: Double Eagle Tanker



82M triangles: 3 Dell PCs with
NVIDIA GeForce 4 cards (2002)

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Recent Work: Use Single GPU for 3 Processes

- Use vertex arrays
- Perform OR, HC and RVG on the GPU
- Improved support for occlusion queries
- Lower performance as compared to 3 GPU-based solution
- Fewer latency problems

[July 2003]

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Live Demo

Dell M50 laptop, 2.4GHz Pentium IV-M CPU, NVIDIA
Quadro4 700GoGL GPU, 1GB memory running
Windows XP: Vertex arrays

Powerplant model (13M triangles)

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View-Dependent Rendering

- Use of static LODs leads to popping artifacts
- Compute a view-dependent simplification
 - ◆ Precompute a vertex and cluster hierarchy
 - ◆ Runtime: perform occlusion culling using cluster hierarchy
 - ◆ Runtime: use the vertex hierarchy to compute the view-dependent simplification

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Integrated Occlusion Culling with View-Dependent Simplification



Single Dell PC with NVIDIA GeForce FX 5800 Ultra GPU
[Yoon, Salomon and Manocha: IEEE Visualization 2003]

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Occlusion-Switch : Advantages

- Generic models
 - ◆ No assumptions on model, distribution
- Conservative Occlusion Culling
- Significant Occlusion Culling
- Low Bandwidth
- Computation performed on GPUs

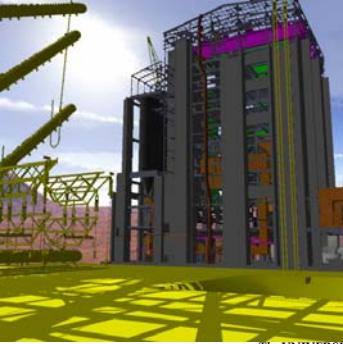
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Outline

- Parallel algorithm using multiple GPUs
- Interactive walkthroughs
- **Interactive shadow generation**

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Interactive Shadows

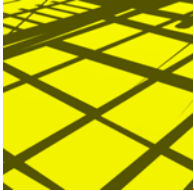


Portions of scene that are occluded from light

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Goal

- Generate hard-edged shadows for interactive walkthroughs
 - ◆ Models with millions of polygons
 - ◆ Scenes with a moving light source



Hard-edged shadows

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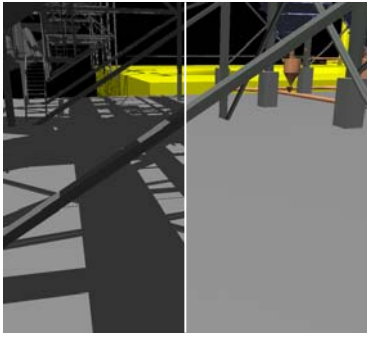
Shadows: Importance

- Realism
 - ◆ Real world scenes have shadows
- Provide a sense of depth to the user
 - ◆ Better navigation
 - ◆ Enhance user experience in interactive games, VR applications

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Shadows: Importance



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Interactive Shadows

N. Govindaraju et al. "Interactive Shadow Generation in Complex Environments", Proc. of ACM SIGGRAPH 2003

Talk scheduled on Tuesday at 3:40pm
(Shadows section)

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Goal

- Generate high fidelity shadows
 - ◆ Requires object precision techniques
 - ◆ Compute shadow casters and shadow receivers

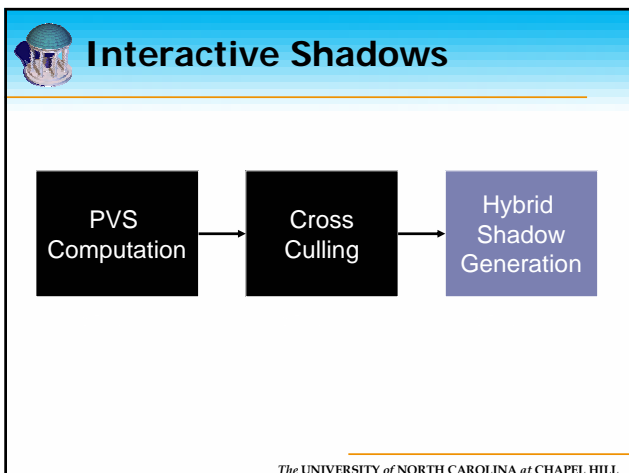
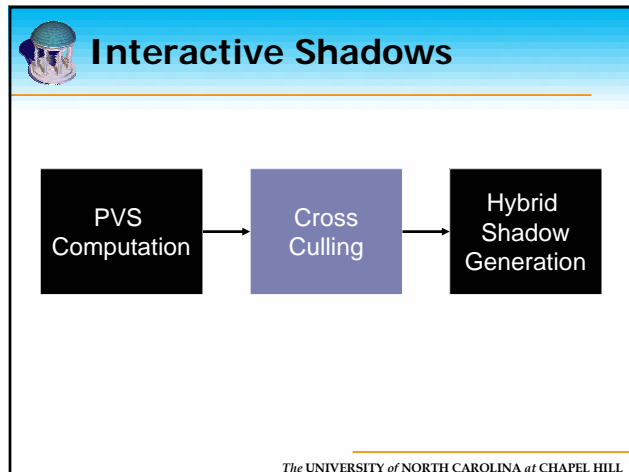
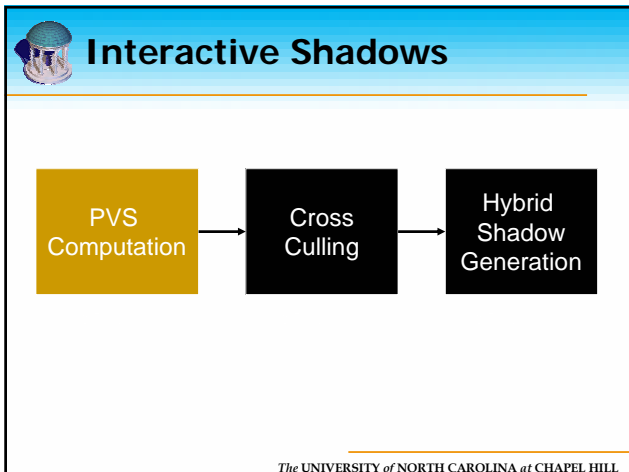
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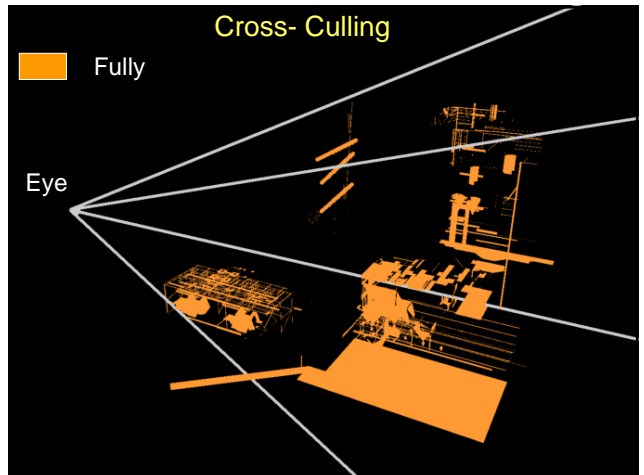
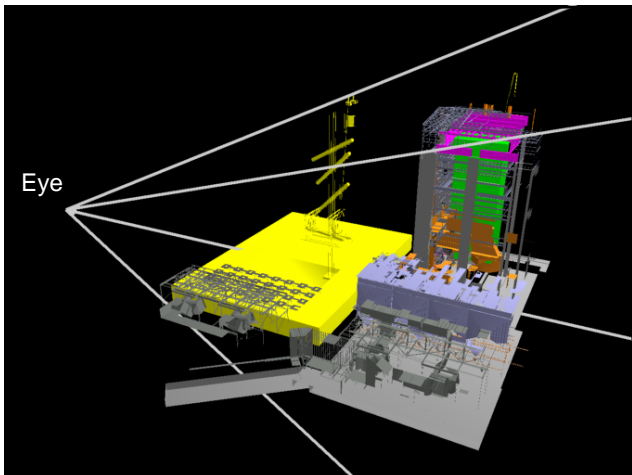
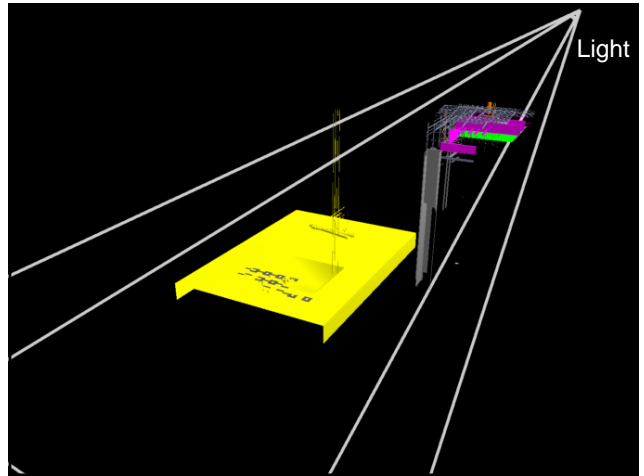
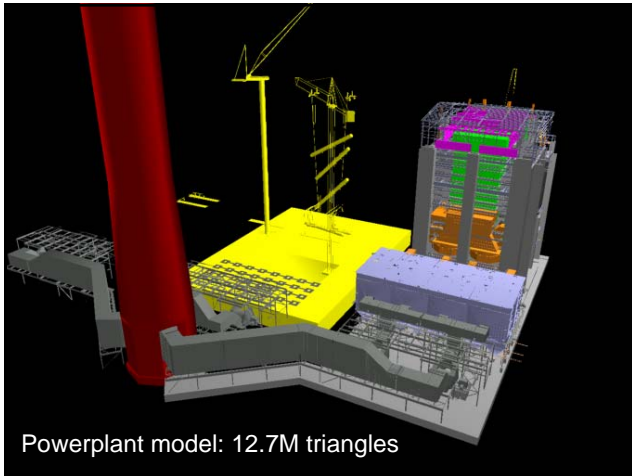
Goal

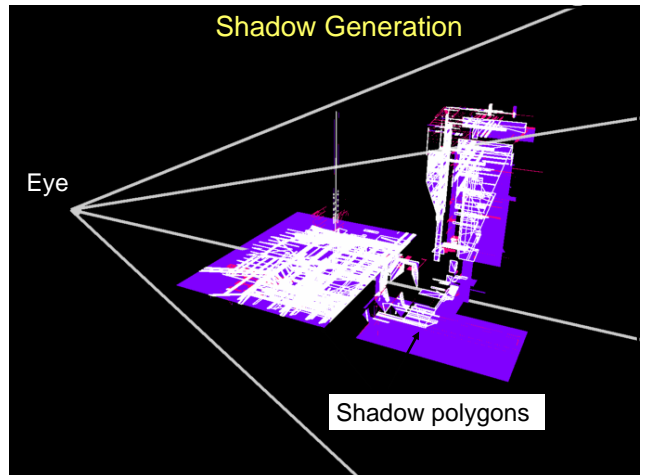
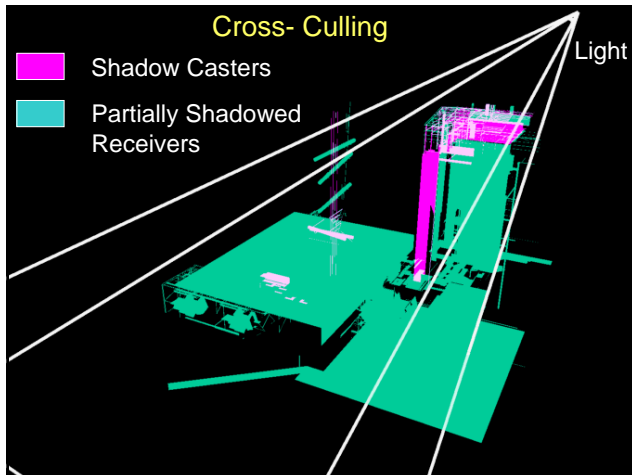
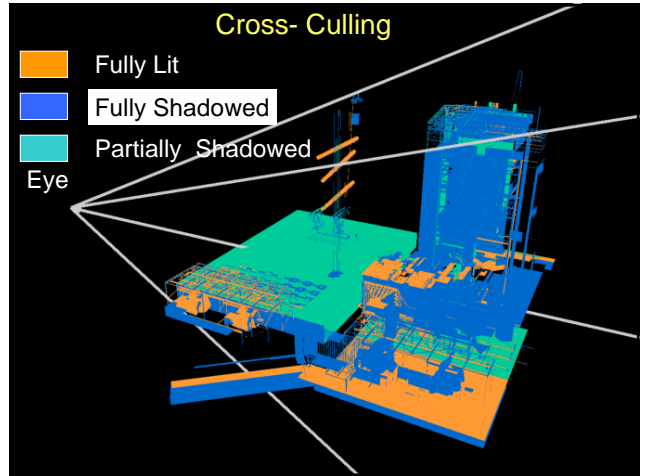
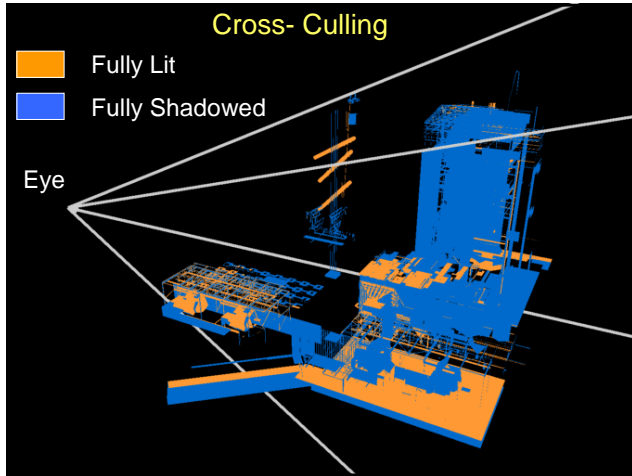
- Interactive performance
 - ◆ Use visibility culling and LOD techniques
 - ◆ Reduce the number of potential shadow casters and shadow receivers

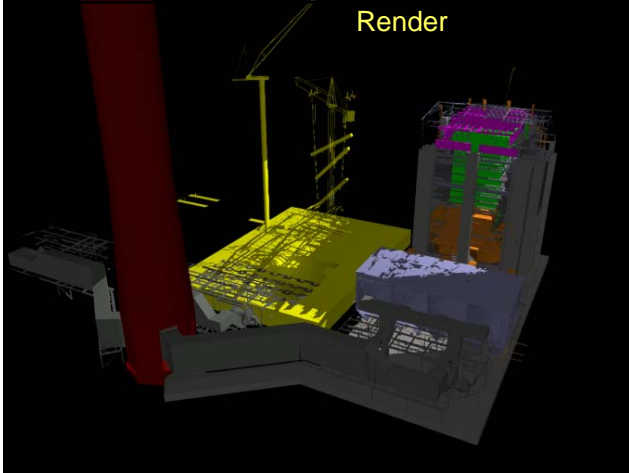
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- ### Overview
- Algorithm proceeds in three stages
 - Stage I: PVS computation
 - ◆ Compute potential shadow casters and receivers
 - Stage II: Cross Culling
 - ◆ Compute shadow casters and receivers that result in aliasing
 - Stage III: Hybrid Shadow Generation
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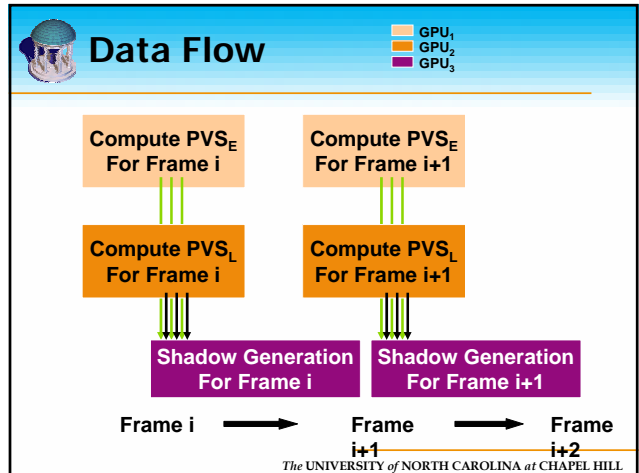
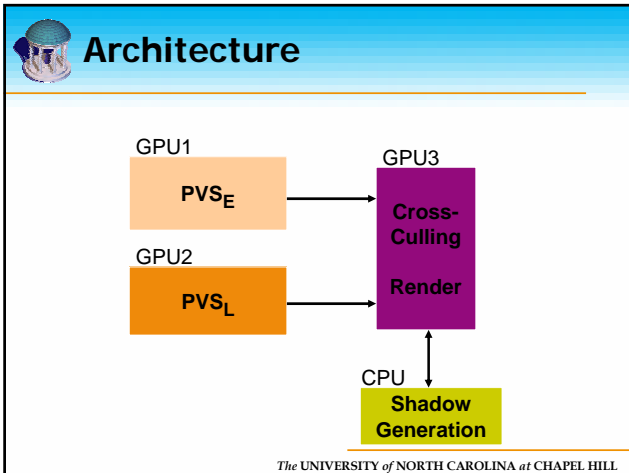





Process-parallel Algorithm

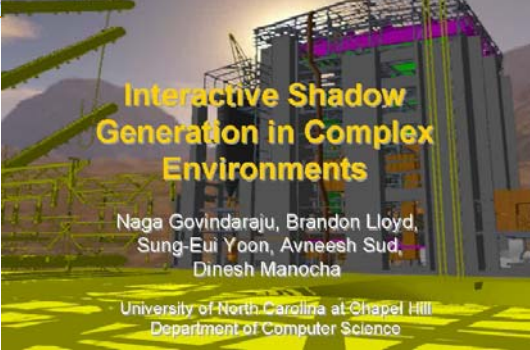
Utilize multiple GPUs to improve performance

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Interactive Shadows




**Interactive Shadow
Generation in Complex
Environments**

Naga Govindaraju, Brandon Lloyd,
Sung-Eui Yoon, Avneesh Sud,
Dinesh Manocha

University of North Carolina at Chapel Hill
Department of Computer Science

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Conclusions

- Interactive display and shadows
- Massive models
- Use multiple GPUs for visibility computations
- Application to complex models

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Collaborators

- Naga Govindaraju
- Brandon Lloyd
- Brian Salomon
- Avneesh Sud
- Sungeui Yoon

<http://www.cs.unc.edu/~walk>



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Acknowledgements

- Army Research Office
- Department of Energy
- Intel Corporation
- Office of Naval Research
- National Science Foundation
- NNS for the DoubleEagle model
- Anonymous donor for Powerplant model
- Boeing Corporation
- NVIDIA Corporation (Occlusion queries)
- UNC Walkthrough group

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The End

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